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Unified EoL Test and Programming via Automotive Bus

Jan Heiber (j.heiber@goepel.com)





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Development motivation Programming strategies End of Line (EoL) Test Mix of Test and EFP Function principle Bus-Controller Integration Practical example Summary





Fundamentals for advanced EoL Solutions



Higher efficiency by synergies...



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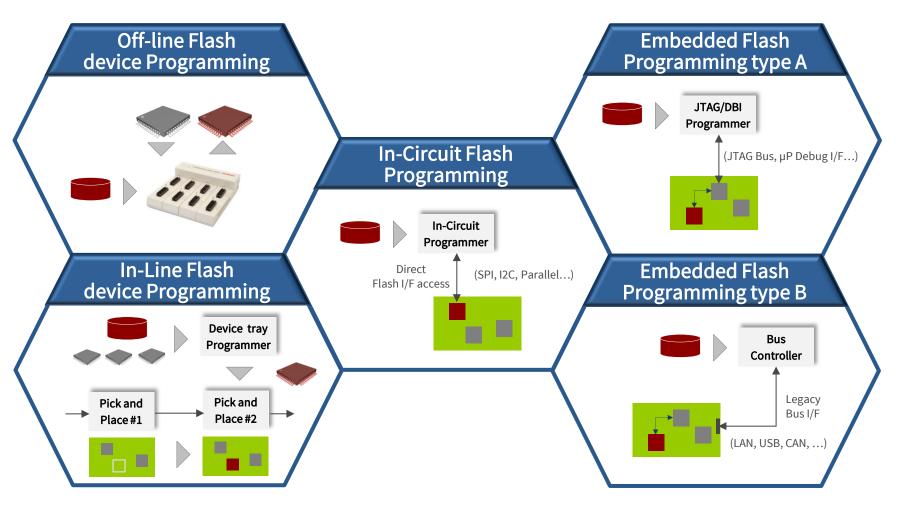
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Why advanced End of Line (EoL) Solutions?

- End of Line test represents a mandatory process step to assure the necessary production quality
- Beyond the EoL test exist the demand for a flexible final configuration of the unit on the same station
- To achieve this level, embedded Flash devices have to be programmed over the native unit interfaces
- Uniform multi-functional platform solutions for test and programming are able to raise production efficiency significant
- Synergies enabling remarkable cost reductions



Different ways – one target

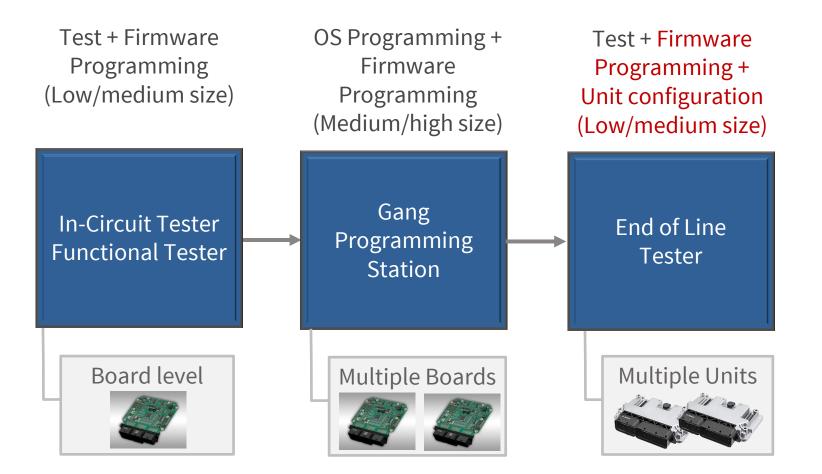


Embedded methods using On-Board resources





Programming on the test floor



EoL-Programming complements existent solutions



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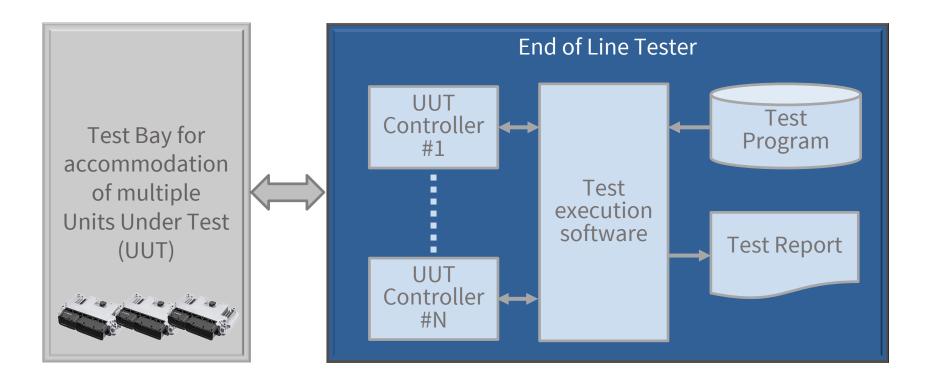


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Basic architecture of an EoL Testers

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- EoL-Test exists to prove final functionality of the units
- Execution of limited function tests (Bus-control)
- Test of multiple Units concurrent is a typical case



Requirements for advanced EoL solutions

- no multiplexing of different system techniques
- Powerful controllers, equal usable for test and programming
- Support of all important automotive bus standards (CAN; CAN-FD; LIN; BroadR-Reach; FlexRay...)
- Easy integration (Plug-Ins) into commercial testexecution software (TestStand, LabVIEW CVI, etc.)
- Support of massive Gang applications
- Comprehensive and comfortable set of commands for test and programming, incl. failure diagnostics



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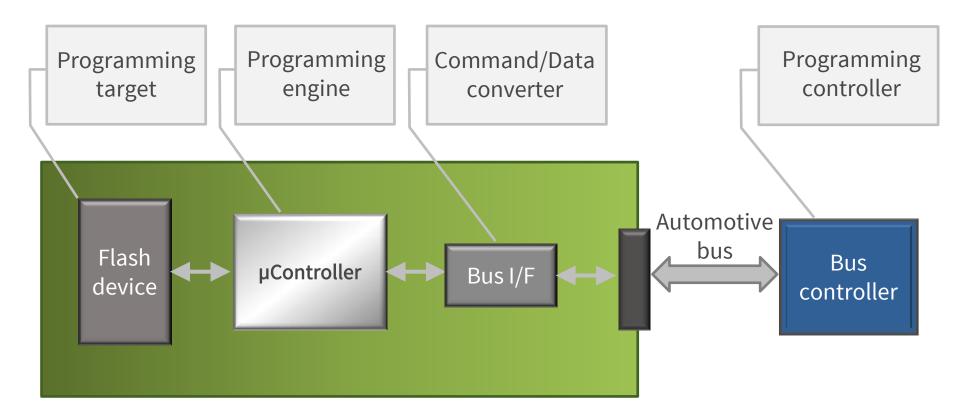
Practice oriented Instrumentation

Platform solutions with highest productivity...





Flash programming via automotive bus



In the programming flow 4 elements are involved

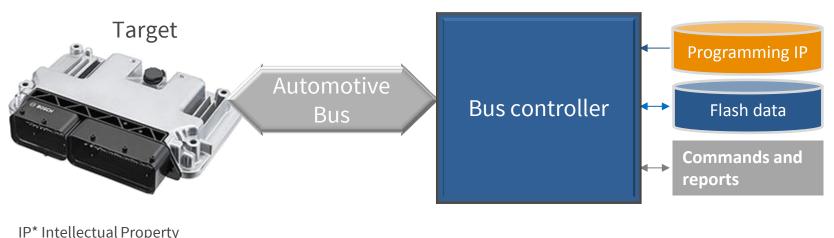




Programming methodology



- Download of a target specific Flash-Programming IP* over the native bus protocol
- Start of the IP in the target
- Data transfer from controller to the IP
- Programming of the Flash by the IP
- Status information returned from IP to controller

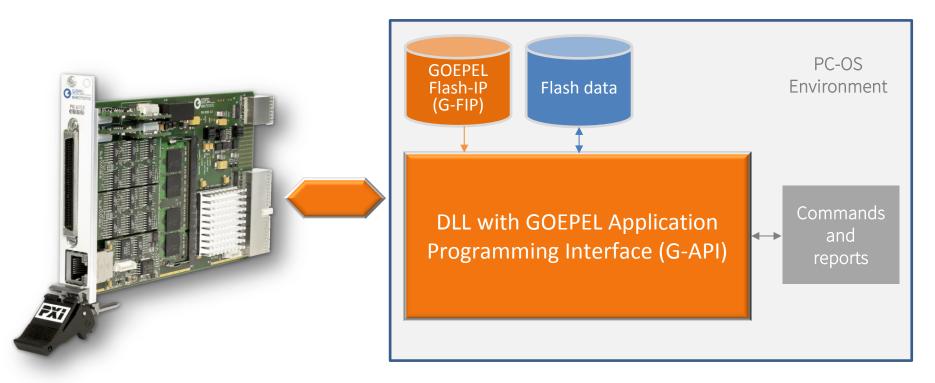




Implemented setup

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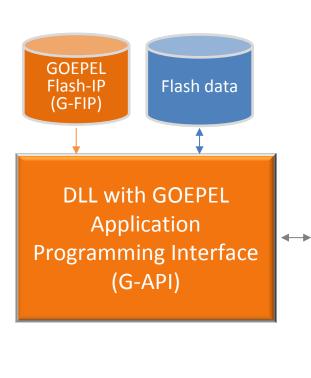
- Generic API includes all commands
- Use of a so called G-FIP (GOEPEL Flash-IP)
- Count of different Flash projects is not limited







Application Programming Interface (API)



Available commands

- System functions
- Security functions
- Test functions for CAN
- Test functions for LIN
- Test functions for FlexRay
- Test functions for LVDS
 - • •
- Diagnostics functions
- Programming functions
 - Erase sectors
 - Blank Check sectors
 - Program data
 - Verify CRC
 - Read data
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In total the API offers over 1000 commands



Vast Bus-Controller portfolio

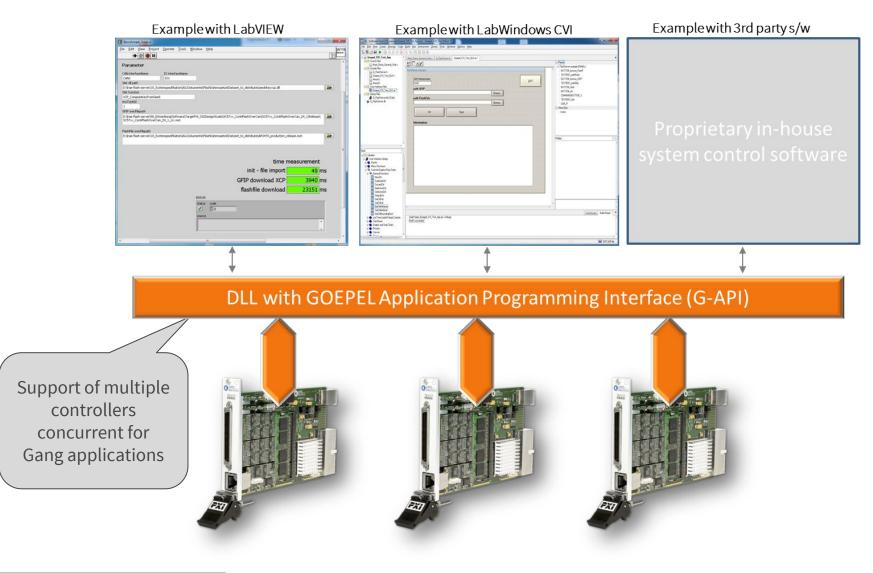


Series 61 comprises over 10 different models





Integration possibilities

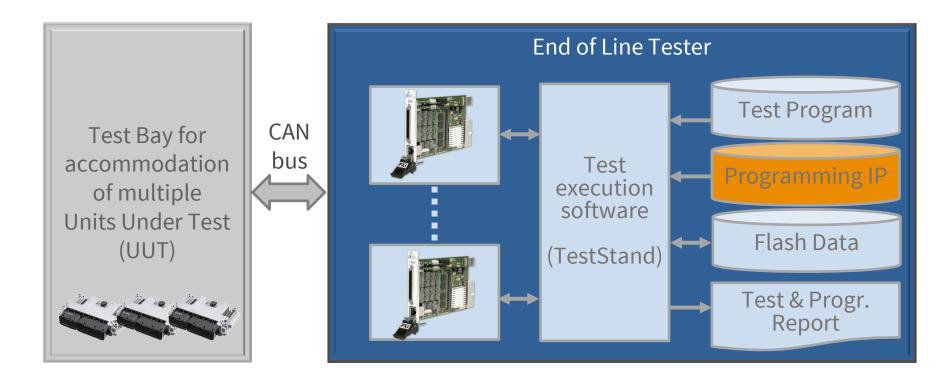






Example of a practical EoL system implementation





- PXI based EoL Platform with Series61 + TestStand
- UUT control via CAN Interface

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Application of XCP-protocol for communication



Achieved results

Procedure	Size/Time	Remark
Image size	1,31MB	1,31MB -> 10,48MBit
Flash-IP download	3,49s	CAN download via XCP Commands
Erase	5,37s	
Blank check	0,18s	
Programming	18,05s	
Verify	0,78s	CRC based
Total Run Time	27,85s	IP download + Erase + Blank check + Program + Verify

µController in the target is a MPC577x derivate









Excellent outlooks...





Summary → Teamwork

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- Combination of test and programming within EoL is an excellent option to increase production flexibility and a valuable complement to other strategies
- Powerful Bus controllers like the Series 61 enable performant platform solutions with scalable throughput via GANG applications
- Complexity of programming requires optimal interaction of software, hardware and IP in conjunction with special automotive expert knowledge







Thanks for your attention!

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